

RS485 protocol for heating.txt

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BaudRate 2400
ByteSize 8 Bit
StopBits 1
Parity None
ParityCheck None

Communication Protocol And DataFormat Describe

Declare: Following " 0X " Mean's HEX Values

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1: Data Package protocol as below:

COMMAND + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

8 Bytes in total

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2: CheckSum definition:

Receive: pc->thermostat;

CheckSum = (command + ID0 + ID1 + Data0 + Data1 + Data2 + Data3) & 0xFF ^ 0xA5 size:
8 Bits

Send: thermostat->pc

CheckSum = (0x50 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + Data4 + Data5 + Data6
+ Data7) & 0xFF ^ 0xA5 size: 8 Bits

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3: COMMAND definition:

Read: PC read data from thermostat

Write: PC transmit data to thermostat

COMMAND is command opcode, size: 8 Bit , commands as below:
command

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PC ----->thermostat

[0XA0] --> : PC read all data from thermostat

[0XA1] --> : PC transmit some data to thermostat

[0XA2] --> : Sensor type selecting

[0XA3] --> : Valve control selecting

[0XA4] --> : Turn on/off

[0XA5] --> : Screen lock

[0XA6] --> : Low temperature protection setting High temperature protection setting

[0XA7] --> : Deadzone temperature setting

[0XA8] --> : Temperature calibration

[0XA9] --> : Temperature setting

[0XAA] --> : Clock setting

[0XAx] --> :

Thermostat----->PC

[0X50] -->: thermostat returns all data to PC

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4: ID0 , ID1 definition :

ID0,ID1 is thermostat's IP address, Hex range is from 0X0000 ~ 0XFFFF :

ID0 is low address

ID1 is high address

ID1 ID0=> 0X0000 is broadcast address. All thermostats could receive data but not respond.

ID1 ID0=> 0X0001-0XFFFF is User address.

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5: Data Package definition :

Data0 ~ Data3/Data 0~ Data 7(A0 command) is command operand , size is 32 Bit (4 Bytes) /64Bit (8 Bytes):

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COMMAND0: 0XA0

Data Package: 0XA0 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 00

Data1 00

Data2 00

Data3 00

For example, IP is 0010, read all data from thermostat, command

A0 10 00 00 00 00 00 15;

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;;-----

Response: 0x50 data returns

COMMAND1: 0XA1

Data package: 0XA1 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => Bit0-Bit1 sensor type

00 -> internal and external sensors

01 -> internal sensor only

10 -> external sensor only

11 -> stand by

Bit2-Bit3 Valve Control Selection

00 -> Valve is controlled by thermostat

01 -> PC open the valve (thermostat can not control)

10 -> PC close the valve (thermostat can not control)

11 -> Standby

Bit4 turn-on/off

0 -> turn-off

1 -> turn-on

Bit5 Lock flag

0->unlock

1->lock

Bit6 low temperature protection flag

0-> need low temperature protection

1-> cancel low temperature protection

Bit7 high temperature protection flag

0-> need high temperature protection

1-> cancel high temperature protection

Data1 => Bit0 lock mode

0-> Buttons are locked except on/off.

1-> All buttons are locked.

Bit1 Lock status

0->unlock

1->lock

Bit2 stand by

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Bit3 stand by

Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => calibration temperature(-9°C~9°C)

Data3 => setting temperature(5°C~35°C)

;;-----

For example: IP is 0010, write data to thermostat: temperature control and limit control(internal sensor and external sensor), control the valve by thermostat; turn on/off, open low temperature protection, open high temperature protection, lock, unlock, set deadzone temperature (1°C), calibration temperature (-1 °C), set temperature (35°C),
command is: A1 10 00 10 10 FF 23 56;

response: 0x50 data returns

;;-----

COMMAND2: 0XA2

Data package: 0XA2 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => Bit0-Bit1 sensor type
 00 -> internal and external sensors
 01 -> internal sensor only
 10 -> external sensor only
 11 -> stand by
Bit2-Bit2 stand by

Data1 => stand by

Data2 => stand by

Data3 => stand by

For example: IP is 0010, change sensor type to external sensor:
command is: A2 10 00 02 00 00 00 11;

response: 0x50 data returns

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COMMAND3: 0XA6

Data package: 0XA3 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

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Data0 => Bit0-Bit1 stand by
 Bit2-Bit3 valve control
 00-> valve is controlled by thermostat
 01-> valve is controlled by PC (thermostat can not control)
 10 -> PC close the valve (thermostat can not control)
 11 -> Standby
 Bit4-Bit7 standby
Data1 => stand by

Data2 => stand by
Data3 => stand by

For example: IP is 0010, valve is controlled by PC,

command is: A3 10 00 08 00 00 00 1E;

For example: IP is 0010, valve is controlled by thermostat,

command is: A3 10 00 00 00 00 00 16;

response: 0x50 data returns

;;-----

COMMAND4: 0XA4

Data package: 0XA4 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => Bit0-Bit3 standby
 Bit 4 Turn on/off
 0 -> turn-off
 1 -> turn-on
 Bit 5-Bit 7 standby

Data1 => standby

Data2 => standby

Data3 => standby

For example, IP is 0010, turn off, command is

A4 10 00 00 00 00 00 11;

For example, IP is 0010, turn on, command is

A4 10 00 10 00 00 00 61;

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response: 0x50 data returns

;;-----

COMMAND5: 0XA5

Data package: 0XA5 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => Bit0-Bit4 standby

Bit 5 Lock Flag

0 -> Unlock

1 -> Lock

Bit 6-Bit 7 standby

Data1 => Bit0 lock mode

0-> Buttons are locked except on/off.

1-> All buttons are locked.

Bit5 Lock

0->unlock

1->lock

Bit 2-Bit 7 standby

Data2 => standby

Data3 => standby

For example, IP is 0010, buttons are locked except on/off, command is

A5 10 00 00 02 00 00 12;

For example, IP is 0010, all buttons are locked, command is

A5 10 00 00 00 00 00 10;

;;-----

response: 0x50 data returns

;;-----

COMMAND6: 0XA6

Data package: 0XA6 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => Bit0-Bit5 standby

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Bit6 low temperature protection flag
0-> need low temperature protection
1-> cancel low temperature protection

Bit7 high temperature protection flag
0-> need high temperature protection
1-> cancel high temperature protection

Data1 => low temperature protection(5°C~10°C)

Data2 => high temperature protection(35°C~70°C)

Data3 => standby

For example, IP is 0010, low temperature protection is 5°C, high temperature protection is 45°C, command is

A6 10 00 00 05 2D 00 4D;

For example, IP is 0010, cancel low temperature protection and high temperature protection, command is

A6 10 00 C0 00 00 00 D3;

;;-----

response: 0x50 data returns

;;-----

COMMAND7: 0XA7

Data package: 0XA7 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => standby

Data1 => Bit0-Bit3 standby
 Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => standby

Data3 => standby

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For example: IP is 0010, deadzone temperature is 2 °C

command is: A7 10 00 00 20 00 00 72;

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response: 0x50 data returns

COMMAND8: 0XA8

Data package: 0XA8 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => standby

Data1 => standby

Data2 => calibration temperature (-9°C~9°C => 0xF7...9)

Data3 => standby

For example, IP is 0010, calibration temperature is 1°C, command is:

A8 10 00 00 00 01 00 1C;

For example, IP is 0010, calibration temperature is -1°C, command is:

A8 10 00 00 00 FF 00 12;

;;-----
response: 0x50 data returns
;;-----

COMMAND9: 0XA9

Data package: 0XA9 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => standby

Data1 => standby

Data2 => standby

Data3 => setting temperature (5°C~35°C)

For example IP is 0010, setting temperature is 32°C, command is :

A9 10 00 00 00 00 20 7C;

;;-----
response: 0x50 data returns
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COMMAND10: 0XAA

Data package: 0XAA + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + CheckSum

Data0 => second (HEX code)

Data1 => minute (HEX code)

Data2 => hour (HEXcode)

Data3 => week (HEXcode)

For example IP is 0010, write time: Wednesday, 03:03, command is

AA 10 00 00 03 03 03 66 ;

;;-----

response: 0x50 data returns

;;-----

;;=====

resposne: 0x50 OK

Data package: 0x50 + ID0 + ID1 + Data0 + Data1 + Data2 + Data3 + Data4 + Data5 + Data6 + Data7 + CheckSum

Data0 => Bit0-Bit1 sensor type

00 -> internal and external sensors

01 -> internal sensor only

10 -> external sensor only

11 -> stand by

Bit2-Bit3 Valve Control Selection

00 -> Valve is controlled by thermostat

01 -> PC open the valve (thermostat can not control)

10 -> PC close the valve (thermostat can not control)

11 -> Standby

Bit4 turn-on/off

0 -> turn-off

1 -> turn-on

Bit5 Lock flag

0->unlock

1->lock

Bit6 low temperature protection flag

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0-> need low temperature protection

1-> cancel low temperature protection

Bit7 high temperature protection flag

0-> need high temperature protection

1-> cancel high temperature protection

Data1 => Bit0 lock mode

0-> Buttons are locked except on/off.

1-> All buttons are locked.

Bit1 Lock status

0->unlock

1->lock

Bit2 Load status

0-> load close

1-> load open

Bit3 Sensor status

0-> sensor normal

1-> sensor error

Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => calibration temperature(-9°C~9°C)

Data3 => setting temperature(5°C~35°C)

Data4 => low temperature protection (5°C~10°C)

Data5 => high temperature protection (35°C~70°C)

Data6 => Room Temperature

Data7 => Floor Temperature

;;=====

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6: Example of 2 commands:

PC is master thermosat is slave

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master read data from thermostat:

COMMAND == 0XA0 PC read data from thermostat
ID0,ID1 => IP

Data0 => 00
Data1 => 00
Data2 => 00
Data3 => 00
Checksum

slave respond

COMMAND == 0X50 thermostat responds data to PC
ID0,ID1 => IP

Data0 => Bit0-Bit1 sensor type
00 -> internal and external sensor
01 -> internal sensor only
10 -> external sensor only
11 -> standby

Bit2-Bit3 Valve Control Selection
00 -> Valve is controlled by thermostat
01 -> PC open the valve (thermostat can not control)
10 -> PC close the valve (thermostat can not control)
11 -> Standby

Bit4 turn-on/off
0 -> turn-off
1 -> turn-on

Bit5 Standby

Bit6 low temperature protection flag
0-> need low temperature protection
1-> cancel low temperature protection

Bit7 high temperature protection flag
0-> need high temperature protection
1-> cancel high temperature protection

Data1 => Bit0 lock mode
0-> Buttons are locked except on/off.
1-> All buttons are locked.

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Bit1 Lock status

0->unlock

1->lock

Bit2 Load status

0-> load close

1-> load open

Bit3 Sensor status

0-> sensor normal

1-> sensor error

Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => calibration temperature(-9°C~9°C)

Data3 => setting temperature(5°C~35°C)

Data4 => low temperature protection (5°C~10°C)

Data5 => high temperature protection (35°C~70°C)

Data6 => Room Temperature

Data7 => Floor Temperature

Checksum

For example send command:

A0 10 00 00 00 00 00 15 ;IP is 0010, read all thermostat data

Feedback:

50 10 00 10 14 FF 23 05 2D 15 1B AD;

thermostat status: turn on, temperature control and limit control(internal sensor and external sensor), control the valve by thermostat, open low temperature protection (5°C), open high temperature protection (45°C), lock, unlock, load open, sensor normal, set deadzone temperature (1°C), calibration temperature (-1 °C), set temperature (35°C), room temperature 21°C, floor temperature 27°C; command is: A1 10 00 10 10 FF 23 56;

response: 0x50 data returns

master write data to thermostat:

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COMMAND == 0XA1 PC write data to thermostat

ID0,ID1 => IP

Data0 => Bit0-Bit1 sensor type
 00 -> internal and external sensor
 01 -> internal sensor only
 10 -> external sensor only
 11 -> standby

Bit2-Bit3 Valve Control Selection
 00 -> Valve is controlled by thermostat
 01 -> PC open the valve (thermostat can not control)
 10 -> PC close the valve (thermostat can not control)
 11 -> Standby

Bit4 turn-on/off
 0 -> turn-off
 1 -> turn-on

Bit5 Standby

Bit6 low temperature protection flag
 0-> need low temperature protection
 1-> cancel low temperature protection

Bit7 high temperature protection flag
 0-> need high temperature protection
 1-> cancel high temperature protection

Data1 => Bit0 lock mode
 0-> Buttons are locked except on/off.
 1-> All buttons are locked.

Bit1 Lock status
 0->unlock
 1->lock

Bit2 Load status
 0-> load close
 1-> load open

Bit3 Sensor status

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0-> sensor normal
1-> sensor error

Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => calibration temperature(-9°C~9°C)

Data3 => setting temperature(5°C~35°C)

Checksum

slave response

COMMAND == 0X50 PC write data to thermostat
ID0,ID1 => IP

Data0 => Bit0-Bit1 sensor type
00 -> internal and external sensor
01 -> internal sensor only
10 -> external sensor only
11 -> standby

Bit2-Bit3 Valve Control Selection
00 -> Valve is controlled by thermostat
01 -> PC open the valve (thermostat can not control)
10 -> PC close the valve (thermostat can not control)
11 -> Standby

Bit4 turn-on/off
0 -> turn-off
1 -> turn-on

Bit5 Standby

Bit6 low temperature protection flag
0-> need low temperature protection
1-> cancel low temperature protection

Bit7 high temperature protection flag
0-> need high temperature protection
1-> cancel high temperature protection

Data1 => Bit0 lock mode
0-> Buttons are locked except on/off.

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1-> All buttons are locked.

Bit1 Lock status
0->unlock
1->lock

Bit2 Load status
0-> load close
1-> load open

Bit3 Sensor status
0-> sensor normal
1-> sensor error

Bit4~bit7 deadzone temperature(1°C~5°C)

Data2 => calibration temperature(-9°C~9°C)

Data3 => setting temperature(5°C~35°C)

Data4 => low temperature protection (5°C~10°C)

Data5 => high temperature protection (35°C~70°C)

Data6 => Room Temperature

Data7 => Floor Temperature

Checksum

For example send command:

A1 10 00 10 10 FF 23 56; IP is 0010, write data to thermostat: temperature control and limit control(internal sensor and external sensor), control the valve by thermostat; turn on/off, open low temperature protection, open high temperature protection, lock, unlock, set deadzone temperature (1°C), calibration temperature (-1 °C), set temperature (35°C),

Feedback:

50 10 00 10 14 FF 23 05 2D 14 1B A2;

thermostat status: turn on, temperature control and limit control(internal sensor and external sensor), control the valve by thermostat, open low temperature protection (5°C), open high temperature protection (45°C), lock, unlock, load open, sensor normal, set deadzone temperature (1°C), calibration temperature (-1 °C), set temperature (35°C), room temperature 21 °C, floor temperature 27°C
